Highly durable and flexible memory based on resistance switching
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1. Introduction

Many flexible devices have been developed for electronic paper, transistors for displays, sensors, solar cells, and organic light emitting diodes [1–3]. Based on this technological trend, the need for a flexible type of memory will also increase to support these flexible electronic devices, similar to the role of flash memory in solid state electronics today. However, most types of flexible memories have been based on organic materials [4–6]. Although organic memory shows good flexibility, its performance cannot match that of conventional flash memory. Additionally, the fabrication process of organic memory is complicated by the requirements of controlled external conditions. These limitations require additional efforts to improve memory performance and increase processing costs.

Recently, resistance random access memory (RRAM) has attracted great attention due to its potential to replace flash memory in next-generation nonvolatile memory applications [7,8]. The resistive switching effect is observed as a result of various insulating materials that consist of CMOS process compatible inorganic materials. In addition, the current–voltage (I–V) characteristics of the simple metal–insulator–metal (MIM) structure exhibit rapid switching speeds and distinctive changes of the resistance between the high resistance state (HRS) and the low resistance state (LRS).

In the present study, the fabrication of a flexible type of RRAM is reported. In an earlier work by the authors, plasma oxidized aluminum [9] and sol–gel derived zinc oxide [10] were used as resistive switching material for flexible type RRAM. On the other hand, in this study, atomic layer deposition (ALD) process is used to improve cell to cell uniformity and for realistic feasibility in flexible memory applications using existing semiconductor technology. The structural simplicity and good ductility of aluminum electrode result in advantages that include good flexibility, mechanical endurance, and durability. In addition, the resistive switching mechanism is investigated by means of a permanent transition from bipolar resistive switching (BRS) to unipolar resistive switching (URS) in TiO₂ films, as understood through γ-ray irradiation effects.

2. Device fabrication

The flexible RRAM was fabricated on the flexible and transparent substrate of polyethersulfone (PES), as shown in Fig. 1. The PES film was glued onto a silicon wafer with polyimide. Aluminum with a thickness of 150 nm was used for the top and bottom electrodes. The electrodes were patterned by conventional photolithography ranging from 2 x 2 to 100 x 100 µm². TiO₂ of 10 nm thickness was used to formulate the resistive switching material. The TiO₂ films were deposited using plasma-enhanced atomic layer deposition at 180 °C. The process temperature of the deposition is limited by the maximum working temperature of PES, which is 200 °C. The thicknesses of the deposited films were confirmed by transmission electron microscopy images. The silicon wafer served only as a mechanical support during the processing stage; it was subsequently peeled off manually after the fabrication of the flexible RRAM.
3. Resistive switching mechanism

3.1. Switching performance

Fig. 2a shows the typical switching characteristics of Al/TiOx/Al that produces BRS. Bias sweeps were conducted in the direction 0 V → −3 V → 0 V → 3 V → 0 V. The current increased sharply at a negative bias (VSET) and switched from HRS to LRS. The LRS remains during the voltage sweep back at a positive bias less than VRESET. The resistance ratio (Ron/Roff) between HRS and LRS is larger than 50 at VREAD = 0.2 V under a compliance current of 500 μA. Fig. 2b shows the measured retention characteristics of the fabricated Al/TiOx/Al devices in the HRS and in the LRS. No significant changes of the resistance in either case were observed after 10^5 s at 85 °C. Additionally, the reliable endurance showing a sustained resistance ratio larger than 50 is achieved even after switching cycles of 10^5 times, as shown in Fig. 2b.

On the one hand, one interesting phenomenon was observed that both BRS and URS could be appeared in TiOx films depending on the current compliance. TiOx films show the BRS mode at a low current compliance (<500 μA) while revealing the URS mode at a high current compliance (>10 mA) after electroforming process, as shown in Fig. 3a. Furthermore, a permanent transition from BRS to URS was observed when a high current (~3 mA) was applied. After the transition of the switching mode, the Ron/Roff value and distribution changed dramatically, as shown in Fig. 3b.

3.2. Oxygen vacancies in TiOx

The inset of Fig. 2a shows a logarithmic plot of the I–V characteristics of TiOx films for BRS mode. In the low-voltage region, the current is linearly proportioned to the voltage (I ∝ V), which is followed by I ∝ V^2. The I ∝ V^2 correlation can be understood as the effect of the space-charge-limited current (SCLC) [11–13]. From a previous analysis by the authors [14], it was verified that the resistive switching of Al/TiOx/Al device was governed by SCLC in the only TiOx layer near the top electrode. However, a suitable physical analysis of TiOx film could not be provided.

To carry out further detail analysis for resistive switching, Fig. 4a shows a transmission electron microscope (TEM) image of the fabricated Al/TiOx/Al device. As shown in Fig. 3a, a TiOx layer with a thickness of 10 nm was deposited initially. However, between the top electrode and the TiOx layer, another layer (~5 nm) was newly generated. To identify this layer, a transmission electron microscope-energy dispersive X-ray spectrometry (TEM–EDX) analysis was carried out. Fig. 4b shows the scanned atom profiling between top and bottom electrode by TEM–EDX analysis. From this data, it is found that an oxygen-deficient layer was preferentially produced in the TiOx layer near the top electrode. A suitable physical analysis of TiOx film could not be provided.
oxygen ions move to the bottom electrode, which generates the additional oxygen vacancies. Consequently, distributed oxygen vacancies induce trap-controlled SCLC and dominantly contribute to the resistive switching. On the other hand, in the case of HRS mode, defects such as oxygen vacancies tend to be aligned to form tiny conducting filaments in the bulk region after electroforming process [18], as shown in Fig. 5b. Although primary oxygen vacancies are localized near the top electrode, oxygen vacancies are redistributed or some defects are newly generated due to the high electric field during electroforming process. These tiny conducting filaments gather together to form stronger and more conducting filaments, which lead to the transition to the LRS. During RESET process, electrons are depleted in some oxygen vacancies (especially near the top electrode) and electron-depleted oxygen vacancies are recombined with O$_2^-$ and C$_0^+$. It has been still in controversy that the HRS current of the URS mode may be transported through the oxide films through hopping conduction [19], Poole–Frenkel emissions [20], or by the space-charge-limited current [21].

3.3. BRS and URS transition and mechanism

Permanent switching mode transition, BRS–URS, according to the current compliance, has been reported elsewhere [22,23] that it was observed restrictedly in titanium oxide material. The first observation of the transition characteristic was reported by Jeong et al. in Pt/TiO$_x$/Pt stack [22]. At that time, however, the only observation of transition was reported and physical analysis was not provided. More intensive analysis was carried out by Wang et al. using analyses of correlation between RESET condition and R$_{on}$ [23]. From correlation between RESET current and R$_{on}$, the URS mode of TiO$_x$ was in accordance with the thermal dissolution model [24], which states that, the conductive filament was thermally destroyed by current crowding and local heating effects during RESET. In addition, the BRS mode of TiO$_x$ can be understood from correlation between RESET voltage and R$_{on}$ by the redox-reaction model [25]. It implies that resistive switching is caused by a local electrochemical redox reaction near the top electrode (anode) interface. These explanations are well consistent with aforementioned switching mechanism of Al/TiO$_x$/Al device.

In this work, to investigate transition characteristic from BRS to URS in detail, γ-irradiation technique was introduced. The total irradiation dose was 100 krad with a dose rate of 50 rad/s. The resistive switching of the TiO$_x$ films was performed in the BRS mode at first. Then, γ-ray was irradiated into the device with $^{60}$Co. Lastly, the URS mode was achieved after mode transition at 3 mA current compliance. The device which showed a transition BRS to URS without γ-irradiation was also investigated as a control group. Fig. 6a shows experimental results that modulation of R$_{on}$
and $R_{\text{off}}$ in a comparison made with and without $\gamma$-irradiation in the URS mode. In the case of the URS mode with $\gamma$-irradiation, only $R_{\text{off}}$ was decreased after switching mode transition. It was known that the valence of the Ti ion varies after irradiation that the Ti$^{3+}$ ion increases in contrast with the Ti$^{4+}$ ion decreases [26]. A fraction of Ti$^{4+}$ ions turns to Ti$^{3+}$ ions and the chemical composition changes as $2\text{TiO}_2 + 2e^- \rightarrow \text{Ti}_2\text{O}_3 + \text{O}_2^-$, hence excess oxygen ions (O$^{-2}$) and oxygen vacancies are created in the irradiated layer.

Consequently, more conducting filaments are formed by $\gamma$-ray induced excess oxygen ions when the switching mode transition was occurred because defects such as oxygen vacancies tend to form conducting filaments. In the case of LRS in the URS mode, there is no significant change between with and without $\gamma$-irradiation. It can be understood that excess filaments has not an important role for current flowing because current mainly flow through the main filaments which connect both electrodes, as shown in Fig. 6b (expected filaments formation is referred to simulation results by random circuit breaker network model [27]). However, in the case of HRS in the URS mode, remained excess filaments cause the leakage current path, so $R_{\text{off}}$ is decreased. This behavior from excess filaments is equivalent to the cell area dependency of the HRS and LRS in URS mode. Generally, in the case of URS, $R_{\text{off}}$ increases as the cell area decreases, whereas $R_{\text{on}}$ is independent of the cell area. It implies that larger cell area device has the more ex-
bends. Even at 105 bends, the amount of oxygen ions and vacancies determines the behavior of resistive switching after transition.

4. Flexibility and mechanical endurance

Good mechanical flexibility is crucial for applications in flexible electronics. The level of mechanical endurance was evaluated by performing a substrate bending test in which both tensile and compressive stresses were induced, as shown in Fig. 7a. A vibrator was used to induce substrate bending 4 times/s for the total of 105 bends. Even at 105 bends, the $R_{on}/R_{off}$ value was unchanged. In addition, the devices exhibited good flexibility, as shown in Fig. 7b. In the flexibility test, severe bending of the device did not affect memory performance. These results indicate that the switching characteristics of flexible RRAM are independent of device bending due to the good ductility of the aluminum electrode and the mechanical endurance arising from the simple device structure.

5. Conclusions

RRAM device was fabricated and showed reliable endurance and retention characteristics, even on a flexible substrate. The transition behavior from BRS to URS was understood with the aid of γ-irradiation. This flexible type of RRAM is attractive for low-cost and wearable devices and may be suitable in flexible displays.

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References


